# Meeting 31.05.16

Reminder 16th June: Video presentation

Demo:

Robot can move around and detect objects, and grab samples.

Last week:

Strategy: The two US sensors work together. Goes around to find a mountain,   
Lower US sensor sometimes detects the grabber

IR detects black, grey and white areas, most of the times. (Try to find a solution for that, maybe aluminum instead than grey, or solder on a bigger resistor).

Communication:

This week:

Next step: One scouting algorithm and one “find the lab” algorithm.

Take a look at the IR sensors.

Hurry up, we were supposed to have final testing this week.

Communication need to be better. Maybe sit down and discuss on Fridays as well.

Task division:

For final report: Need documentation for testing.

AOB:

Next week: Start on video presentation. On that Friday, start filming. Make something pleasing to look at, a good presentation is important.